

Register Transfer Language And Micro Operations:

Register Transfer language:

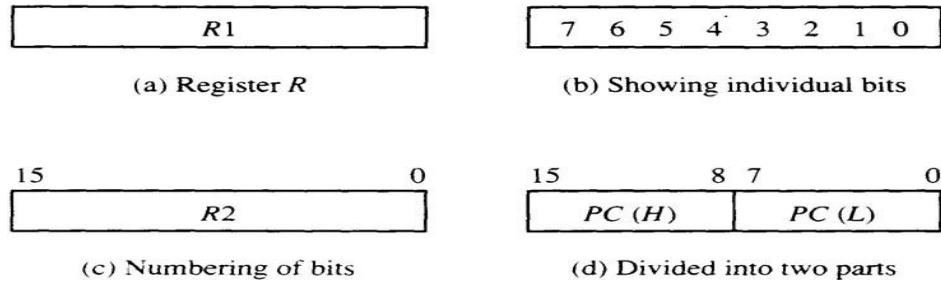
- Digital systems are composed of modules that are constructed from digital components, such as registers, decoders, arithmetic elements, and control logic
- The modules are interconnected with common data and control paths to form a digital computer system
- The operations executed on data stored in registers are called microoperations
- A microoperation is an elementary operation performed on the information stored in one or more registers
- Examples are shift, count, clear, and load
- Some of the digital components from before are registers that implement microoperations
- The internal hardware organization of a digital computer is best defined by specifying
 - The set of registers it contains and their functions
 - The sequence of microoperations performed on the binary information stored
 - The control that initiates the sequence of microoperations
- Use symbols, rather than words, to specify the sequence of microoperations
- The symbolic notation used is called a register transfer language
- A programming language is a procedure for writing symbols to specify a given computational process
- Define symbols for various types of microoperations and describe associated hardware that can implement the microoperations

Register Transfer

- Designate computer registers by capital letters to denote its function
- The register that holds an address for the memory unit is called MAR
- The program counter register is called PC

- IR is the instruction register and R1 is a processor register
- The individual flip-flops in an n-bit register are numbered in sequence from 0 to n-1
- Refer to Figure 4.1 for the different representations of a register

Figure 4-1 Block diagram of register.



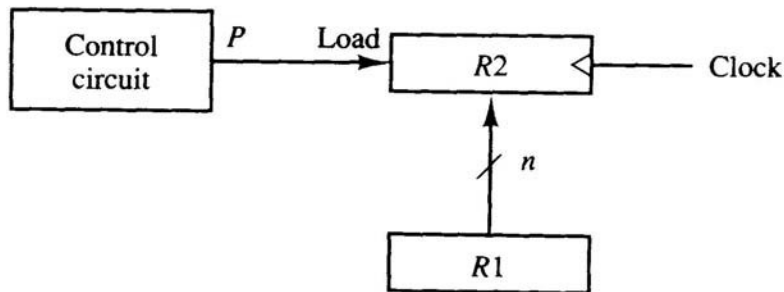
- Designate information transfer from one register to another by $R2 \leftarrow R1$
- This statement implies that the hardware is available
 - The outputs of the source must have a path to the inputs of the destination
 - The destination register has a parallel load capability
- If the transfer is to occur only under a predetermined control condition, designate it by
 - If ($P = 1$) then ($R2 \leftarrow R1$)
 or,
 - $P: R2 \leftarrow R1,$

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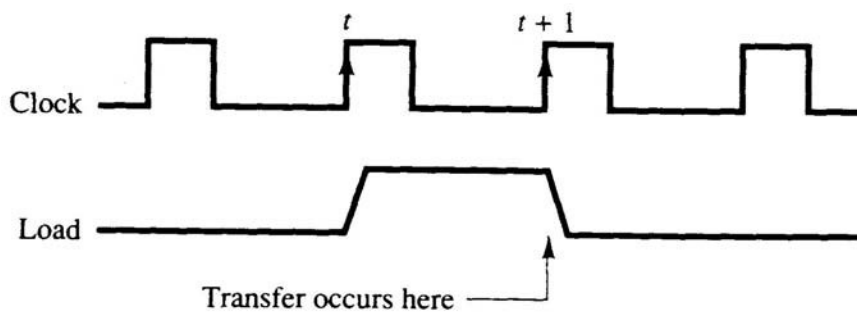
where P is a control function that can be either 0 or 1

- Every statement written in register transfer notation implies the presence of the required hardware construction

Figure 4-2 Transfer from $R1$ to $R2$ when $P = 1$.



(a) Block diagram



(b) Timing diagram

- It is assumed that all transfers occur during a clock edge transition
- All microoperations written on a single line are to be executed at the same time $T: R2 \leftarrow R1, R1 \leftarrow R2$

TABLE 4-1 Basic Symbols for Register Transfers

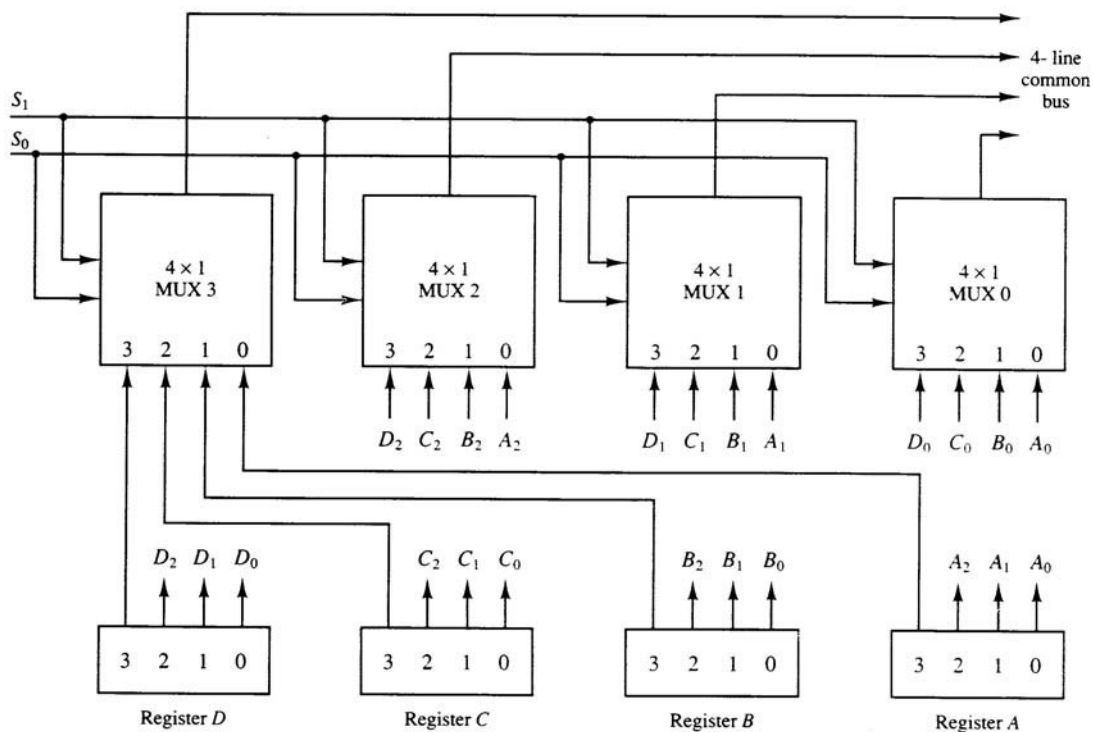
Symbol	Description	Examples
Letters (and numerals)	Denotes a register	$MAR, R2$
Parentheses ()	Denotes a part of a register	$R2(0-7), R2(L)$
Arrow \leftarrow	Denotes transfer of information	$R2 \leftarrow R1$
Comma ,	Separates two microoperations	$R2 \leftarrow R1, R1 \leftarrow R2$

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Bus and Memory Transfers

- Rather than connecting wires between all registers, a common bus is used
- A bus structure consists of a set of common lines, one for each bit of a register
- Control signals determine which register is selected by the bus during each transfer
- Multiplexers can be used to construct a common bus
- Multiplexers select the source register whose binary information is then placed on the bus
- The select lines are connected to the selection inputs of the multiplexers and choose the bits of one register

Figure 4-3 Bus system for four registers.



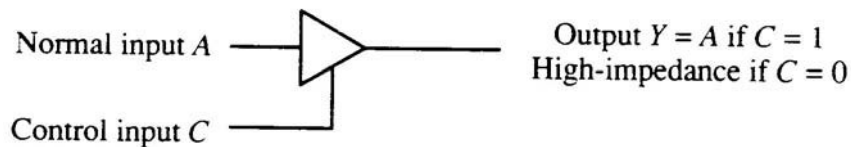
- In general, a bus system will multiplex k registers of n bits each to produce an n -line common bus
- This requires n multiplexers – one for each bit
- The size of each multiplexer must be $k \times 1$
- The number of select lines required is $\log k$
- To transfer information from the bus to a register, the bus lines are connected to the inputs of all destination registers and the corresponding load control line must be activated
- Rather than listing each step as

$$\text{BUS} \leftarrow C, R1 \leftarrow \text{BUS},$$
 use $R1 \leftarrow C$, since the bus is implied
- Instead of using multiplexers, three-state gates can be used to

construct the bus system

- A three-state gate is a digital circuit that exhibits three states
- Two of the states are signals equivalent to logic 1 and 0
- The third state is a high-impedance state – this behaves like an open circuit, which means the output is disconnected and does not have a logic significance

Figure 4-4 Graphic symbols for three-state buffer.



- The three-state buffer gate has a normal input and a control input which determines the output state
- With control 1, the output equals the normal input
- With control 0, the gate goes to a high-impedance state
- This enables a large number of three-state gate outputs to be connected with wires to form a common bus line without endangering loading effects

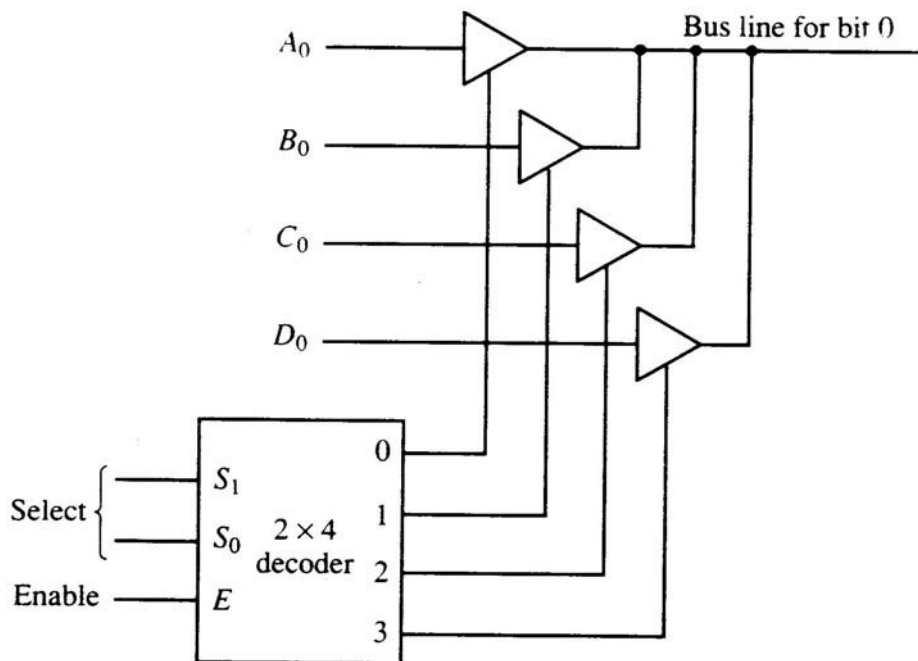


Figure 4-5 Bus line with three state-buffers.

- Decoders are used to ensure that no more than one control input is active at any given time
- This circuit can replace the multiplexer in Figure 4.3
- To construct a common bus for four registers of n bits each using three-state buffers, we need n circuits with four buffers in each
- Only one decoder is necessary to select between the four registers
- Designate a memory word by the letter M
- It is necessary to specify the address of M when writing memory transfer operations

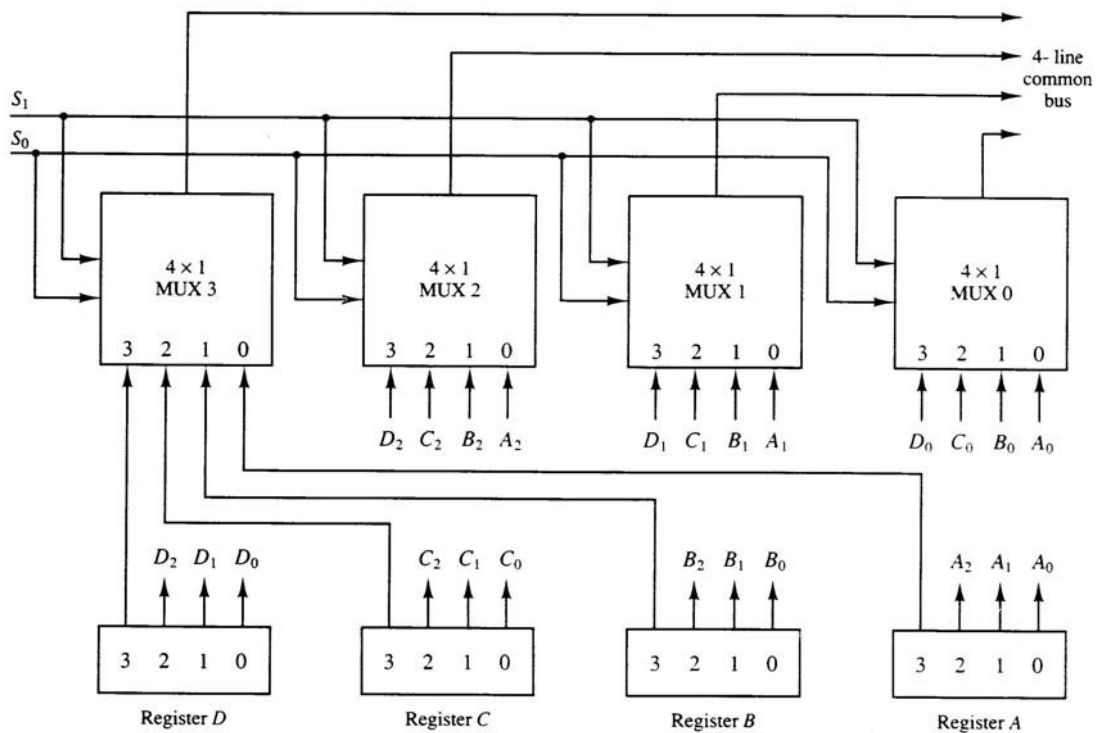
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- Designate the address register by AR and the data register by DR
- The read operation can be stated as: Read: $DR \leftarrow M[AR]$
- The write operation can be stated as:
Write: $M[AR] \leftarrow R1$

Arithmetic Microoperations

- There are four categories of the most common microoperations:
 - Register transfer: transfer binary information from one register to another
 - Arithmetic: perform arithmetic operations on numeric data stored in registers
 - Logic: perform bit manipulation operations on non-numeric data stored in registers
 - Shift: perform shift operations on data stored in registers
- The basic arithmetic microoperations are addition, subtraction, increment, decrement, and shift
- Example of addition: $R3 \leftarrow R1 + R2$
- Subtraction is most often implemented through complementation and addition
- Example of subtraction: $R3 \leftarrow R1 + \overline{R2} + 1$ (strikethrough denotes bar on top – 1's complement of R2)
- Adding 1 to the 1's complement produces the 2's complement
- Adding the contents of R1 to the 2's complement of R2 is equivalent to subtracting

Figure 4-3 Bus system for four registers.



- Multiply and divide are not included as microoperations
- A microoperation is one that can be executed by one clock pulse
- Multiply (divide) is implemented by a sequence of add and shift microoperations (subtract and shift)
- To implement the add microoperation with hardware, we need the registers that hold the data and the digital component that performs the addition
- A full-adder adds two bits and a previous carry
- A binary adder is a digital circuit that generates the arithmetic sum of two binary numbers of any length
- A binary adder is constructed with full-adder circuits connected in cascade
- An n-bit binary adder requires n full-adders

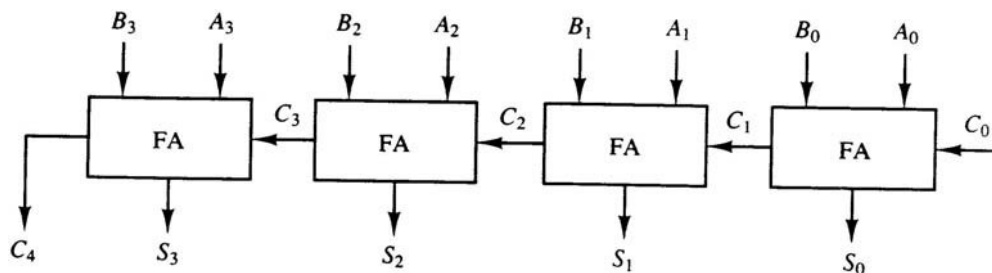


Figure 4-6 4-bit binary adder.

- The subtraction $A-B$ can be carried out by the following steps
 - Take the 1's complement of B (invert each bit)

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- Get the 2's complement by adding 1
- Add the result to A
- The addition and subtraction operations can be combined into one common circuit by including an XOR gate with each full-adder

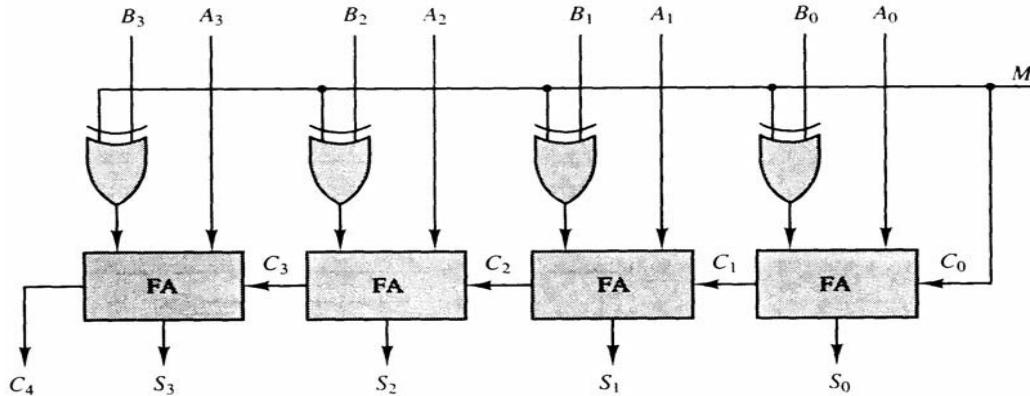


Figure 4-7 4-bit adder-subtractor.

- The increment microoperation adds one to a number in a register
- This can be implemented by using a binary counter – every time the count enable is active, the count is incremented by one
- If the increment is to be performed independent of a particular register, then use half-adders connected in cascade
- An n-bit binary incrementer requires n half-adders

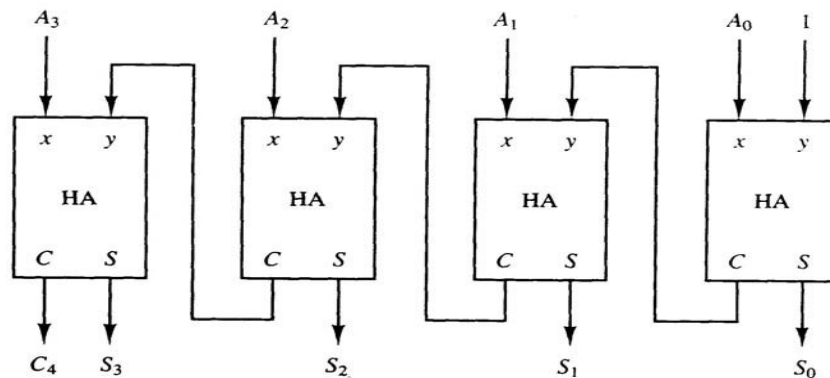


Figure 4-8 4-bit binary incrementer.

- Each of the arithmetic microoperations can be implemented in one composite arithmetic circuit
- The basic component is the parallel adder
- Multiplexers are used to choose between the different operations
- The output of the binary adder is calculated from the following sum: $D = A + Y + C_{in}$

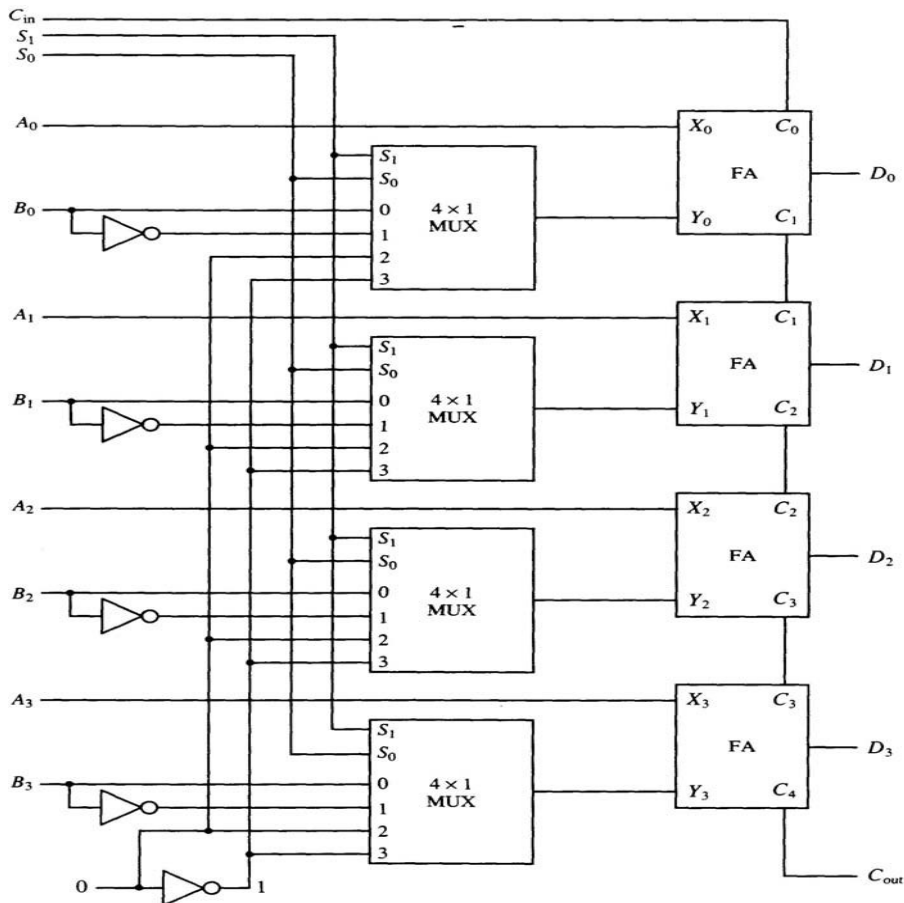


Figure 4-9 4-bit arithmetic circuit.

TABLE 4-4 Arithmetic Circuit Function Table

Select			Input Y	Output $D = A + Y + C_{in}$	Microoperation
S_1	S_0	C_{in}			
0	0	0	B	$D = A + B$	Add
0	0	1	B	$D = A + B + 1$	Add with carry
0	1	0	\bar{B}	$D = A + \bar{B}$	Subtract with borrow
0	1	1	\bar{B}	$D = A + \bar{B} + 1$	Subtract
1	0	0	0	$D = A$	Transfer A
1	0	1	0	$D = A + 1$	Increment A
1	1	0	1	$D = A - 1$	Decrement A
1	1	1	1	$D = A$	Transfer A

Logic Microoperations

- Logic operations specify binary operations for strings of bits stored in registers and treat each bit separately
- Example: the XOR of R1 and R2 is symbolized by

$$P: R1 \leftarrow R1 \oplus R2$$

- Example: R1 = 1010 and R2 = 1100
 1010 Content of R1
 1100 Content of R2

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0110 Content of R1 after P = 1

- Symbols used for logical microoperations:
 - OR: \mathbf{V}
 - AND: $\mathbf{\wedge}$
 - XOR: $\mathbf{\oplus}$
- The + sign has two different meanings: logical OR and summation
- When + is in a microoperation, then summation
- When + is in a control function, then OR
- Example:

$P + Q: R1 \leftarrow R2 + R3, R4 \leftarrow R5 \mathbf{V} R6$
- There are 16 different logic operations that can be performed with two binary variables

TABLE 4-5 Truth Tables for 16 Functions of Two Variables

<i>x</i>	<i>y</i>	<i>F</i> ₀	<i>F</i> ₁	<i>F</i> ₂	<i>F</i> ₃	<i>F</i> ₄	<i>F</i> ₅	<i>F</i> ₆	<i>F</i> ₇	<i>F</i> ₈	<i>F</i> ₉	<i>F</i> ₁₀	<i>F</i> ₁₁	<i>F</i> ₁₂	<i>F</i> ₁₃	<i>F</i> ₁₄	<i>F</i> ₁₅
0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1
0	1	0	0	0	0	1	1	1	1	0	0	0	0	1	1	1	1
1	0	0	0	1	1	0	0	1	1	0	0	1	1	0	0	1	1
1	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1

TABLE 4-6 Sixteen Logic Microoperations

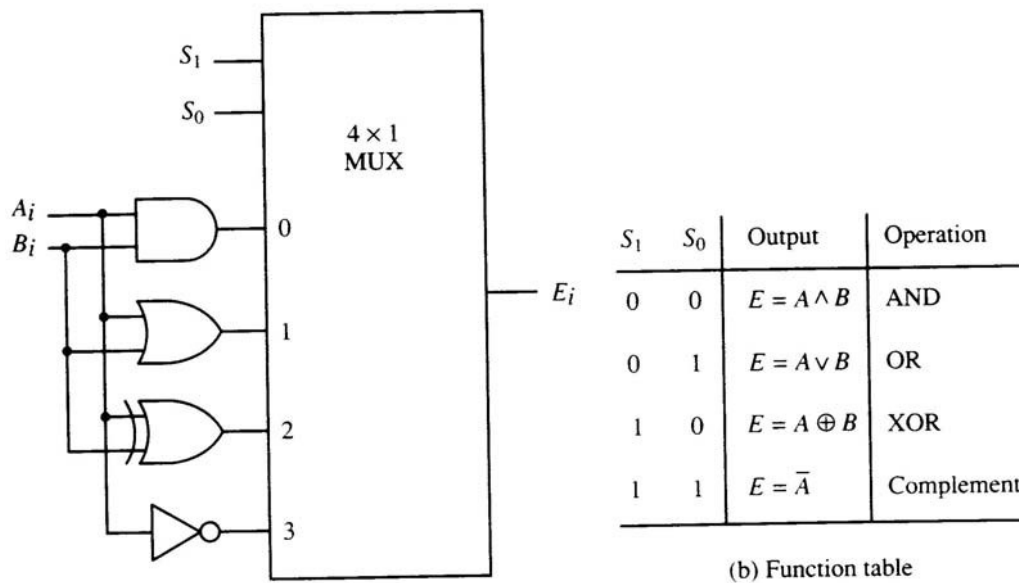
Boolean function	Microoperation	Name
$F_0 = 0$	$F \leftarrow 0$	Clear
$F_1 = xy$	$F \leftarrow A \wedge B$	AND
$F_2 = xy'$	$F \leftarrow A \wedge \overline{B}$	
$F_3 = x$	$F \leftarrow A$	Transfer A
$F_4 = x'y$	$F \leftarrow \overline{A} \wedge B$	
$F_5 = y$	$F \leftarrow B$	Transfer B
$F_6 = x \oplus y$	$F \leftarrow A \oplus B$	Exclusive-OR
$F_7 = x + y$	$F \leftarrow A \vee B$	OR
$F_8 = (x + y)'$	$F \leftarrow \overline{A \vee B}$	NOR
$F_9 = (x \oplus y)'$	$F \leftarrow \overline{A \oplus B}$	Exclusive-NOR
$F_{10} = y'$	$F \leftarrow \overline{B}$	Complement B
$F_{11} = x + y'$	$F \leftarrow A \vee \overline{B}$	
$F_{12} = x'$	$F \leftarrow \overline{A}$	Complement A
$F_{13} = x' + y$	$F \leftarrow \overline{A} \vee B$	
$F_{14} = (xy)'$	$F \leftarrow \overline{A \wedge B}$	NAND
$F_{15} = 1$	$F \leftarrow \text{all 1's}$	Set to all 1's

- The hardware implementation of logic microoperations requires that logic gates be inserted for each bit or pair of bits in the registers

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- All 16 microoperations can be derived from using four logic gates

Figure 4-10 One stage of logic circuit.



(a) Logic diagram

(b) Function table

- Logic microoperations can be used to change bit values, delete a group of bits, or insert new bit values into a register
- The selective-set operation sets to 1 the bits in A where there are corresponding 1's in B

1010 A before
 $\underline{1100}$ B
 1110 A after

$$A \leftarrow A \square B$$

- The selective-complement operation complements bits in A where there are corresponding 1's in B

1010 A before
 $\underline{1100}$ B
 0110 A after

$$A \leftarrow A \oplus B$$

- The selective-clear operation clears to 0 the bits in A only where there are corresponding 1's in B

1010 A before
 $\underline{1100}$ B
 0010 A after

$$A \leftarrow A \square B$$

- The mask operation is similar to the selective-clear operation, except that the bits of A are cleared only where there are corresponding 0's in B

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1010 A before
1100 B
1000 A
A ←

A □ B

- The insert operation inserts a new value into a group of bits
- This is done by first masking the bits to be replaced and then Oring them with the bits to be inserted

0110 1010 A before
0000 1111 B (mask)
0000 1010 A after masking

0000 1010 A before
1001 0000 B (insert)
1001 1010 A after insertion

- The clear operation compares the bits in A and B and produces an all 0's result if the two number are equal

1010 A
1010 B
0000 A ← A ⊕ B

Shift Microoperations

- Shift microoperations are used for serial transfer of data
- They are also used in conjunction with arithmetic, logic, and other data- processing operations
- There are three types of shifts: logical, circular, and arithmetic
- A logical shift is one that transfers 0 through the serial input
- The symbols shl and shr are for logical shift-left and shift-right by one position $R1 \leftarrow \text{shl}R1$

- The circular shift (aka rotate) circulates the bits of the register around the two ends without loss of information
- The symbols cil and cir are for circular shift left and right

TABLE 4-7 Shift Microoperations

Symbolic designation	Description
$R \leftarrow \text{shl } R$	Shift-left register R
$R \leftarrow \text{shr } R$	Shift-right register R
$R \leftarrow \text{cil } R$	Circular shift-left register R
$R \leftarrow \text{cir } R$	Circular shift-right register R
$R \leftarrow \text{ashl } R$	Arithmetic shift-left R
$R \leftarrow \text{ashr } R$	Arithmetic shift-right R

- The arithmetic shift shifts a signed binary number to the left or right
- To the left is multiplying by 2, to the right is dividing by 2
- Arithmetic shifts must leave the sign bit unchanged
- A sign reversal occurs if the bit in R_{n-1} changes in value after the shift
- This happens if the multiplication causes an overflow
- An overflow flip-flop V_s can be used to detect

$$\text{the overflow } V_s = R_{n-1} \oplus R_{n-2}$$

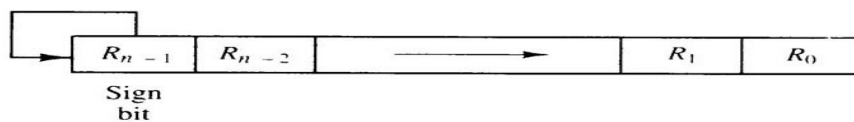


Figure 4-11 Arithmetic shift right.

- A bi-directional shift unit with parallel load could be used to implement this
- Two clock pulses are necessary with this configuration: one to load the value and another to shift
- In a processor unit with many registers it is more efficient to implement the shift operation with a combinational circuit
- The content of a register to be shifted is first placed onto a common bus and the output is connected to the combinational shifter, the shifted number is then loaded back into the register
- This can be constructed with multiplexers

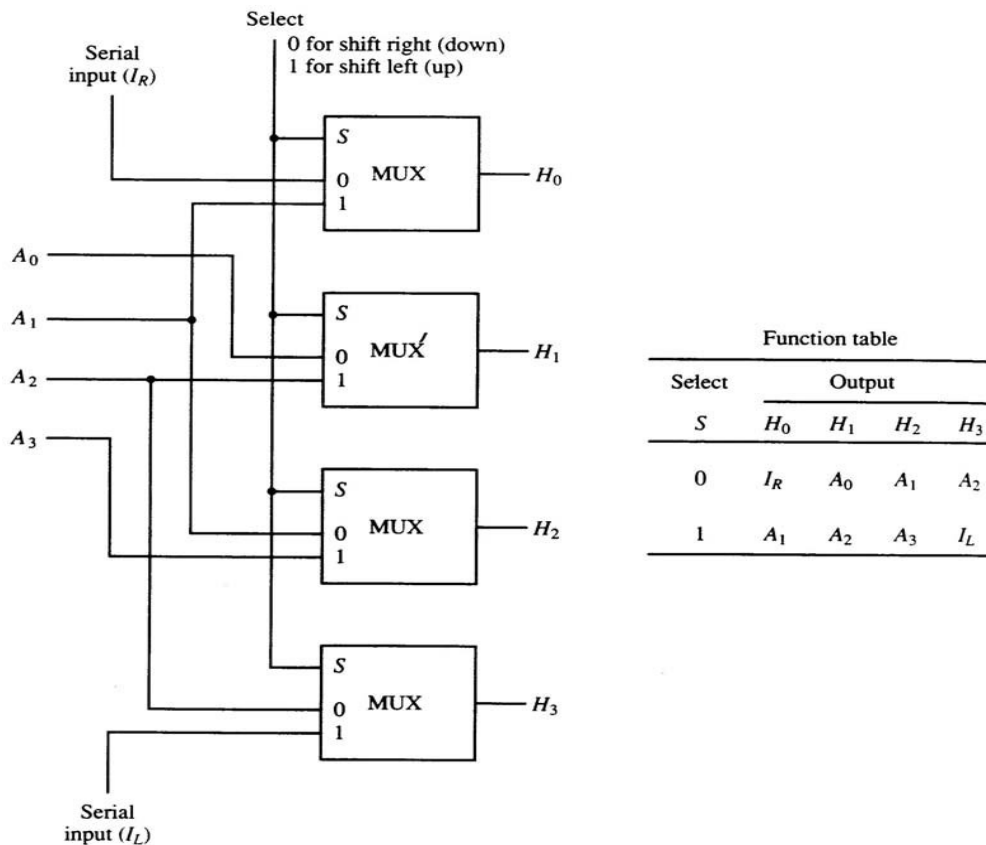


Figure 4-12 4-bit combinational circuit shifter.

Arithmetic Logic Shift Unit

- The arithmetic logic unit (ALU) is a common operational unit connected to a number of storage registers
- To perform a microoperation, the contents of specified registers are placed in the inputs of the ALU
- The ALU performs an operation and the result is then transferred to a destination register
- The ALU is a combinational circuit so that the entire register transfer operation from the source registers through the ALU and into the destination register can be performed during one clock pulse period

Figure 4-13 One stage of arithmetic logic shift unit.

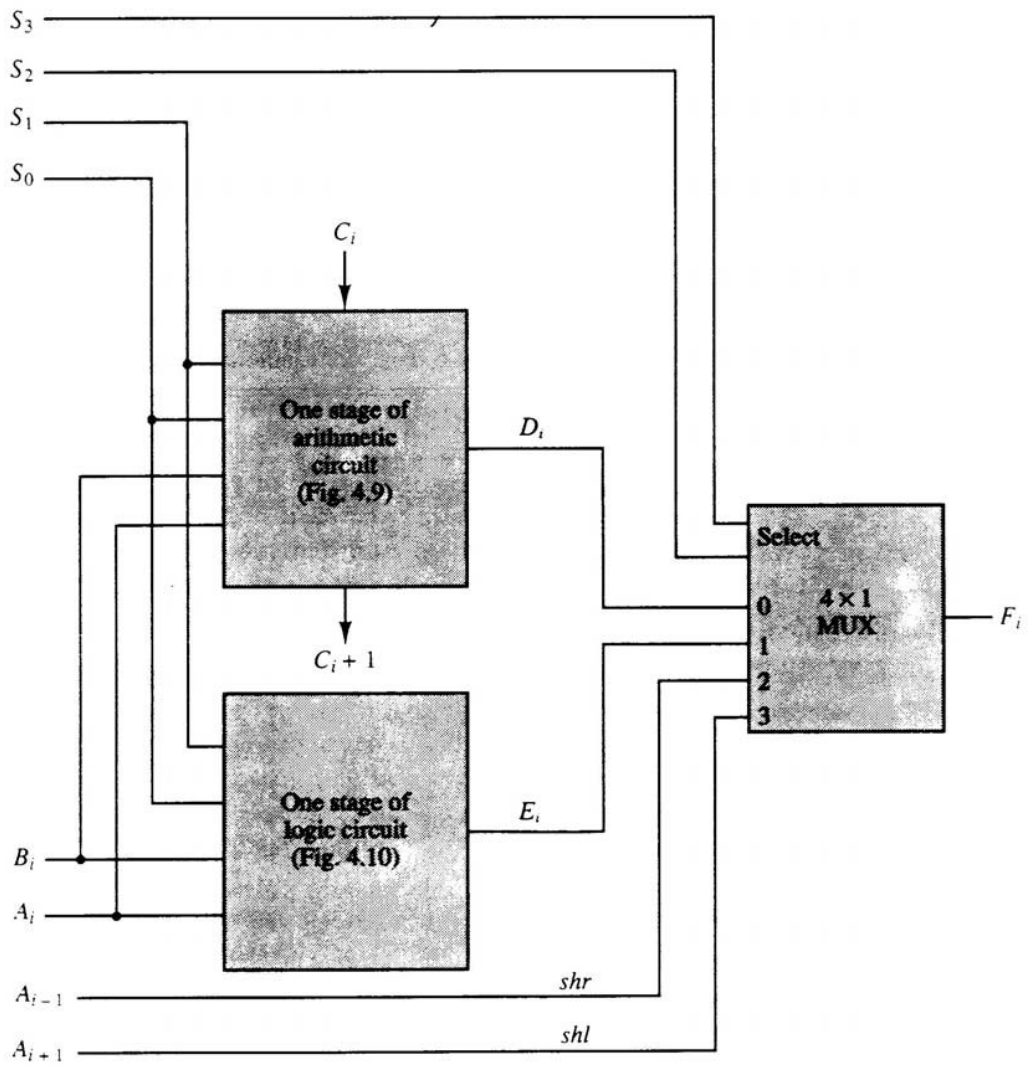


TABLE 4-8 Function Table for Arithmetic Logic Shift Unit

Operation select					Operation	Function
S_3	S_2	S_1	S_0	C_{in}		
0	0	0	0	0	$F = A$	Transfer A
0	0	0	0	1	$F = A + 1$	Increment A
0	0	0	1	0	$F = A + B$	Addition
0	0	0	1	1	$F = A + B + 1$	Add with carry
0	0	1	0	0	$F = A + \overline{B}$	Subtract with borrow
0	0	1	0	1	$F = A + \overline{B} + 1$	Subtraction
0	0	1	1	0	$F = A - 1$	Decrement A
0	0	1	1	1	$F = A$	Transfer A
0	1	0	0	×	$F = A \wedge B$	AND
0	1	0	1	×	$F = A \vee B$	OR
0	1	1	0	×	$F = A \oplus B$	XOR
0	1	1	1	×	$F = \overline{A}$	Complement A
1	0	×	×	×	$F = \text{shr } A$	Shift right A into F
1	1	×	×	×	$F = \text{shl } A$	Shift left A into F